

NOTE: COLLATERAL CONSTRAINTS, EMERGING MARKET BUSINESS CYCLES, AND R&D ACTIVITIES

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July 24, 2007

[QUESTION] Can the collateral constraint in R&D activities account for the features of the emerging economy?

- Emerging market business cycles exhibit strongly counter-cyclical current accounts, consumption volatility that exceeds income volatility, and “ sudden stops ” in capital inflows. (Auiar and Gopnath, 2006)

[APPROACH]

- We construct a dynamic general equilibrium model with R&D activities à la Romer (1990).
- In our model, the working capital for the production of effective labor is subject to the collateral constraint because of *the lack of a commitment* problem à la Kiyotaki and Moore (1997).
- Consider the collateral constraints are binding in the emerging economies while they are not binding in the developed ones.
- R&D technology, δ_A , tightness of collateral constraint, ϕ , and Hicks neutral stationary technology level, ζ are exogenous and AR(1) process.
- Investigate the impulse responses to R&D technology and TFP growth.

[RESULTS]

- The impulse responses of binding and not-binding constraints are almost same. The labor inputs' responses of binding case are bigger than those of not-binding case. (Our hypothesis is rejected.)

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1. THE MODEL

HOUSEHOLDS:

$$\max_{c_t, n_t, i_t, k_t} E_0 \sum_{t=0}^{\infty} \beta^t \frac{[c_t^{1-\xi} (1-n_t)^\xi]^{1-\varepsilon}}{1-\varepsilon}, \quad (1)$$

$$\text{s.t. } c_t + i_t = w_t n_t + r_{k,t} k_{t-1} + \pi_t, \quad (2)$$

$$k_t = (1 - \delta_k) k_{t-1} + i_t. \quad (3)$$

EFFECTIVE LABOR PRODUCER:

$$\max_{z_{A,t}, z_{y,t}, n_{A,t}, n_{y,t}, a_t} E_0 \sum_{t=0}^{\infty} \beta^t \lambda_t \left[\hat{w}_t (z_{A,t} + z_{y,t}) - w_t (n_{A,t} + n_{y,t}) + (r_{a,t} + q_t) a_{t-1} - q_t a_t \right], \quad (4)$$

$$\text{s.t. } z_{A,t} = n_{A,t}, \quad (5)$$

$$z_{y,t} = n_{y,t}, \quad (6)$$

$$w_t (n_{A,t} + n_{y,t}) = \phi q_t a_{t-1}. \quad (7)$$

FINAL GOODS FIRMS:

$$\max_{y_t, z_{y,t}, a_{t-1}, x_t} \left[y_t - \hat{w}_t z_{y,t} - r_{a,t} a_{t-1} - \int_0^{A_{t-1}} p_t(i) x_t(i) di \right], \quad (8)$$

$$\text{s.t. } y_t = \zeta z_{y,t}^{(1-\gamma)(1-\alpha)} a_{t-1}^{(1-\gamma)\alpha} \left[\int_0^{A_{t-1}} x_t(i) di \right]. \quad (9)$$

INTERMEDIATE GOODS FIRMS:

$$P_{A,t}(i) = \frac{1}{\beta^t \lambda_t} E_t \sum_{s=t}^{\infty} \beta^s \lambda_s \left[p_s(i) x_s(i) - \eta r_{k,s} x_s(i) \right]. \quad (10)$$

R&D FIRMS:

$$\max_{z_{A,t}} \sum_{t=0}^{\infty} \beta^t \lambda_t \left[P_{A,t} \delta_A A_t - \hat{w}_t \right] z_{A,t}. \quad (11)$$

MARKET CLEARING CONDITIONS:

$$c_t + i_t = y_t, \quad (12)$$

$$n_{A,t} + n_{y,t} = n_t, \quad (13)$$

$$a_t = 1, \quad (14)$$

$$A_t = (\delta_A z_{A,t} + 1) A_{t-1}. \quad (15)$$

2. EQUILIBRIUM SYSTEM

The equilibrium system *with binding collateral constraint* is

$$c_t^{(1-\xi)(1-\varepsilon)-1} (1 - n_t)^{\xi(1-\varepsilon)} = \lambda_t, \quad (16)$$

$$w_t = \frac{\xi}{1-\xi} \cdot \frac{c_t}{1-n_t}, \quad (17)$$

$$1 = \beta E_t \left[\frac{\lambda_{t+1}}{\lambda_t} (1 + r_{k,t+1} - \delta_k) \right], \quad (18)$$

$$\hat{w}_t = w_t(1 + \theta_t), \quad (19)$$

$$q_t = \beta E_t \left[\frac{\lambda_{t+1}}{\lambda_t} \left\{ r_{a,t+1} + q_{t+1} + \phi \theta_{t+1} q_{t+1} \right\} \right], \quad (20)$$

$$w_t n_t = \phi q_t, \quad (21)$$

$$\hat{w}_t = (1 - \gamma)(1 - \alpha) \frac{y_t}{n_{y,t}}, \quad (22)$$

$$r_{a,t} = (1 - \gamma)\alpha y_t, \quad (23)$$

$$p_t = \gamma n_{y,t}^{(1-\gamma)(1-\alpha)} x_t^{\gamma-1}, \quad (24)$$

$$x_t = \left[\frac{\gamma^2}{\eta r_{k,t}} \right]^{\frac{1}{1-\gamma}} n_{y,t}^{1-\alpha}, \quad (25)$$

$$\hat{w}_t = P_{A,t} \delta_A A_{t-1}, \quad (26)$$

$$n_{y,t} + n_{A,t} = n_t, \quad (27)$$

$$c_t + i_t = y_t, \quad (28)$$

$$A_t = (\delta_{A,t} n_{A,t} + 1) A_{t-1}, \quad (29)$$

$$y_t = \zeta \frac{A_{t-1}^{1-\gamma}}{\eta^\gamma} n_{y,t}^{(1-\gamma)(1-\alpha)} k_{t-1}^\gamma, \quad (30)$$

$$k_{t-1} = \eta x_t A_{t-1}, \quad (31)$$

$$k_t = (1 - \delta_k) k_{t-1} + i_t, \quad (32)$$

$$P_{A,t} = E_t \left[\beta \frac{\lambda_{t+1}}{\lambda_t} P_{A,t+1} + p_t x_t - \eta r_{k,t} x_t \right]. \quad (33)$$

There are 18 equations and 18 variables:

$$c_t, n_t, n_{A,t}, n_{y,t}, \theta_t, \lambda_t, q_t, k_t, i_t, \\ w_t, \hat{w}_t, r_{k,t}, r_{a,t}, p_t, x_t, y_t, P_{A,t}, A_t.$$

For the de-trended system, we introduce the following notations:

$$\tilde{\psi}_t := \frac{\psi_t}{A_{t-1}}, \quad (34)$$

for $\psi_t = c_t, q_t, k_t, i_t, w_t, r_{a,t}, y_t$,¹ and

$$\tilde{\lambda}_t := \frac{\lambda_t}{A_{t-1}^{(1-\xi)(1-\varepsilon)-1}}. \quad (35)$$

¹Note that the variety of goods (or TFP) in the period t is determined at the previous period: A_{t-1} .

The de-trended system is

$$\tilde{c}_t^{(1-\xi)(1-\varepsilon)-1}(1-n_t)^{\xi(1-\varepsilon)} = \tilde{\lambda}_t, \quad (36)$$

$$\tilde{w}_t = \frac{\xi}{1-\xi} \cdot \frac{\tilde{c}_t}{1-n_t}, \quad (37)$$

$$1 = \beta E_t \left[\frac{\tilde{\lambda}_{t+1}}{\tilde{\lambda}_t} (1+g_t)^{(1-\xi)(1-\varepsilon)-1} (1+r_{k,t+1}-\delta_k) \right], \quad (38)$$

$$\tilde{q}_t = \beta E_t \left[\frac{\tilde{\lambda}_{t+1}}{\tilde{\lambda}_t} (1+g_t)^{(1-\xi)(1-\varepsilon)} \left\{ \tilde{r}_{a,t+1} + \tilde{q}_{t+1} + \phi \theta_{t+1} \tilde{q}_{t+1} \right\} \right], \quad (39)$$

$$\tilde{w}_t n_t = \phi \tilde{q}_t, \quad (40)$$

$$\tilde{w}_t (1+\theta_t) = (1-\gamma)(1-\alpha) \frac{\tilde{y}_t}{n_{y,t}}, \quad (41)$$

$$\tilde{r}_{a,t} = (1-\gamma)\alpha \tilde{y}_t, \quad (42)$$

$$p_t = \gamma n_{y,t}^{(1-\gamma)(1-\alpha)} x_t^{\gamma-1}, \quad (43)$$

$$x_t = \left[\frac{\gamma^2}{\eta r_{k,t}} \right]^{\frac{1}{1-\gamma}} n_{y,t}^{1-\alpha}, \quad (44)$$

$$\tilde{w}_t (1+\theta_t) = P_{A,t} \delta_A, \quad (45)$$

$$n_{y,t} + n_{A,t} = n_t, \quad (46)$$

$$\tilde{c}_t + \tilde{i}_t = \tilde{y}_t, \quad (47)$$

$$g_t = \delta_{A,t} n_{A,t}, \quad (48)$$

$$\tilde{y}_t = \zeta \frac{1}{\eta^\gamma} n_{y,t}^{(1-\gamma)(1-\alpha)} \left[\frac{\tilde{k}_{t-1}}{1+g_{t-1}} \right]^\gamma, \quad (49)$$

$$\tilde{k}_{t-1} = \eta x_t (1+g_{t-1}), \quad (50)$$

$$\tilde{k}_t = \frac{1-\delta_k}{1+g_{t-1}} \tilde{k}_{t-1} + \tilde{i}_t, \quad (51)$$

$$P_{A,t} = E_t \left[\beta \frac{\tilde{\lambda}_{t+1}}{\tilde{\lambda}_t} (1+g_t)^{(1-\xi)(1-\varepsilon)-1} P_{A,t+1} + p_t x_t - \eta r_{k,t} x_t \right]. \quad (52)$$

where

$$g_{t+1} := \ln \left(\frac{A_{t+1}}{A_t} \right). \quad (53)$$

On the balanced growth path, this system becomes

$$\tilde{c}^{(1-\xi)(1-\varepsilon)-1}(1-n)^{\xi(1-\varepsilon)} = \tilde{\lambda}, \quad (54)$$

$$\tilde{w} = \frac{\xi}{1-\xi} \cdot \frac{\tilde{c}}{1-n}, \quad (55)$$

$$1 = \beta(1+g)^{(1-\xi)(1-\varepsilon)-1}(1+r_k - \delta_k), \quad (56)$$

$$\tilde{q} = \beta(1+g)^{(1-\xi)(1-\varepsilon)} \left\{ \tilde{r}_a + \tilde{q} + \phi\theta\tilde{q} \right\}, \quad (57)$$

$$\tilde{w}n = \phi\tilde{q}, \quad (58)$$

$$\tilde{w}(1+\theta) = (1-\gamma)(1-\alpha)\frac{\tilde{y}}{n_y}, \quad (59)$$

$$\tilde{r}_a = (1-\gamma)\alpha\tilde{y}, \quad (60)$$

$$p = \gamma n_y^{(1-\gamma)(1-\alpha)} x^{\gamma-1}, \quad (61)$$

$$x = \left[\frac{\gamma^2}{\eta r_k} \right]^{\frac{1}{1-\gamma}} n_y^{1-\alpha}, \quad (62)$$

$$\tilde{w}(1+\theta) = P_A \delta_A, \quad (63)$$

$$n_y + n_A = n, \quad (64)$$

$$\tilde{c} + \tilde{i} = \tilde{y}, \quad (65)$$

$$g = \delta_A n_A, \quad (66)$$

$$\tilde{y} = \zeta \frac{1}{\eta^\gamma} n_y^{(1-\gamma)(1-\alpha)} \left[\frac{\tilde{k}}{1+g} \right]^\gamma, \quad (67)$$

$$\tilde{k} = \eta x(1+g), \quad (68)$$

$$\left[1 - \frac{1-\delta_k}{1+g} \right] \tilde{k} = \tilde{i}, \quad (69)$$

$$\left[1 - \beta(1+g)^{(1-\xi)(1-\varepsilon)-1} \right] P_A = (p - \eta r_k)x. \quad (70)$$

There are 17 equations and 17 variables:

$$\begin{aligned} &\tilde{c}, n, n_A, n_y, \theta, \tilde{\lambda}, \tilde{q}, \tilde{k}, \tilde{i}, \\ &\tilde{w}, r_k, \tilde{r}_a, p, x, \tilde{y}, P_A, g. \end{aligned}$$

EQUILIBRIUM SYSTEM WITHOUT COLLATERAL CONSTRAINT : If the collateral constraint is not binding, $\theta_t = 0$. The equilibrium system is (16) - (33) except (21) with $\theta_t = 0$. The de-trended system and the balanced growth path system are analogues of those under collateral constraints except (40) and (58) with $\theta_t = 0$ and $\theta = 0$, respectively.

REFERENCES

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TABLE 1: PARAMETER VALUES

parameter	symbol	value
discount factor	β	.99
curvature of utility function	ε	.6
weight of leisure in utility	ξ	.6
relative share of land to labor in production	α	.01
share of capital in production	γ	.36
steady-state technology growth	\bar{g}	.01/4
depreciation rate of capital	δ_k	.025
steady-state tightness of collateral constraint	ϕ	.1
persistence of R&D technology growth	ρ_{δ_A}	.95
persistence of production technology level	ρ_{ζ}	.95
persistence of tightness of collateral constraint	ρ_{ϕ}	.95

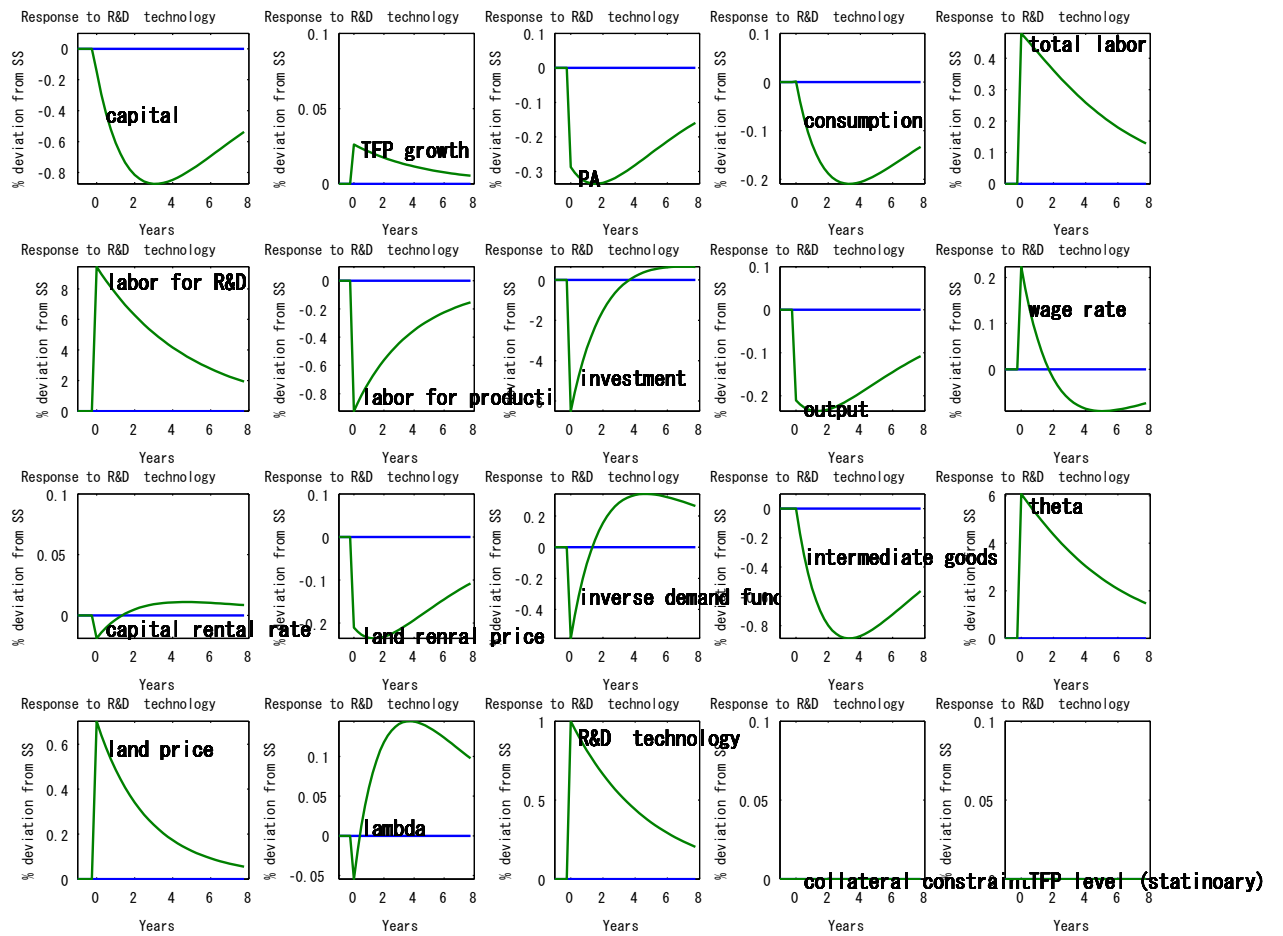


FIGURE 1: IMPULSE RESPONSE TO R&D TECHNOLOGY LEVEL; BINDING COLLATERAL CONSTRAINT

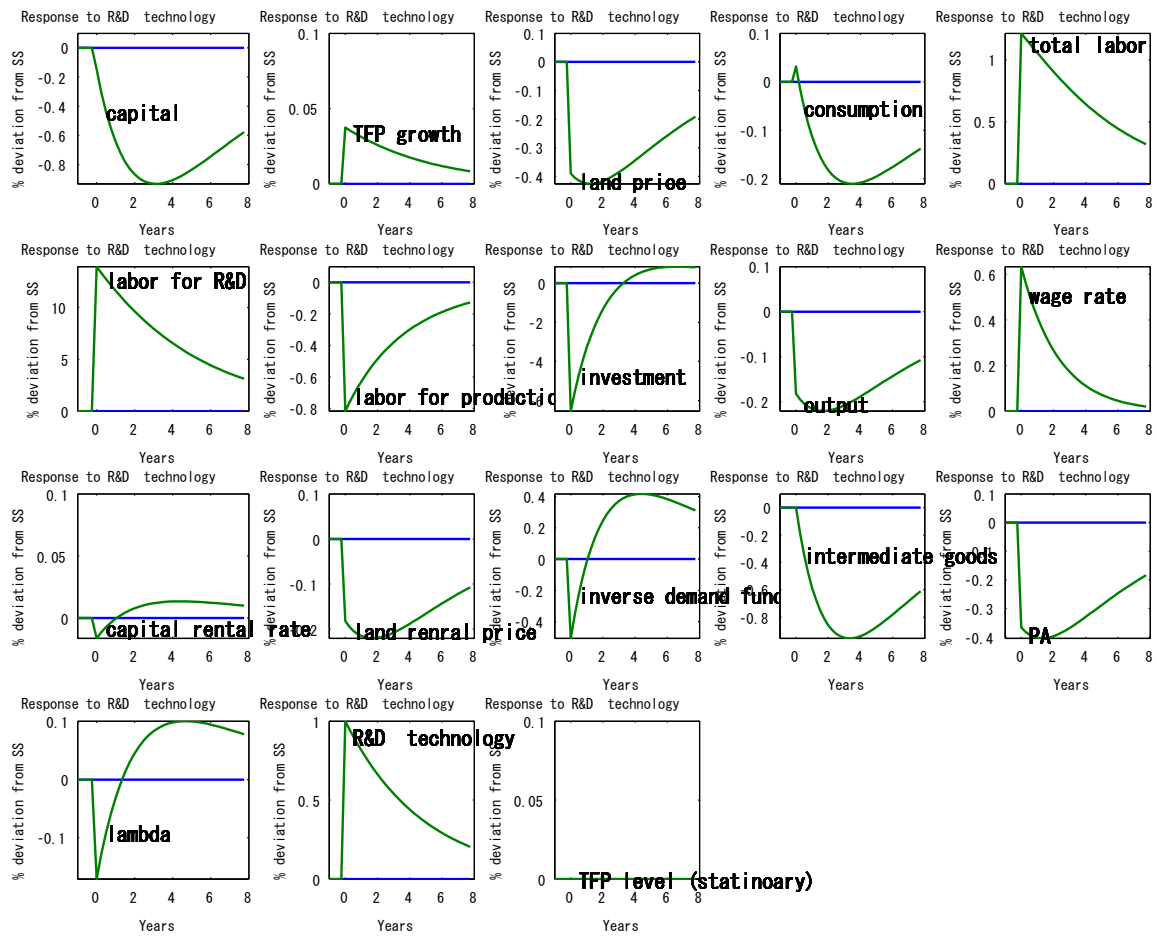


FIGURE 2: IMPULSE RESPONSE TO R&D TECHNOLOGY LEVEL; NO COLLATERAL CONSTRAINT

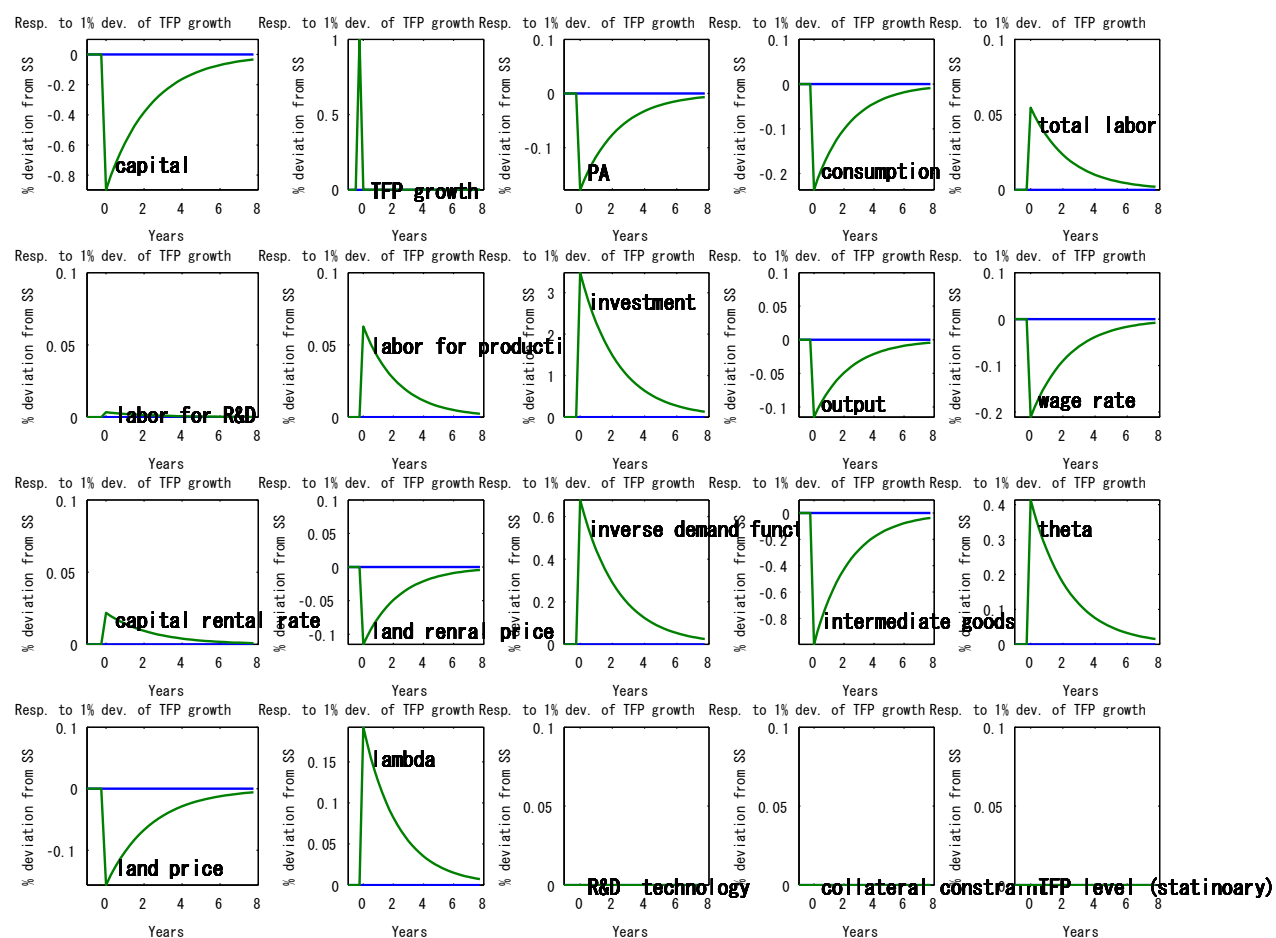


FIGURE 3: IMPULSE RESPONSE TO TFP GROWTH; BINDING COLLATERAL CONSTRAINT

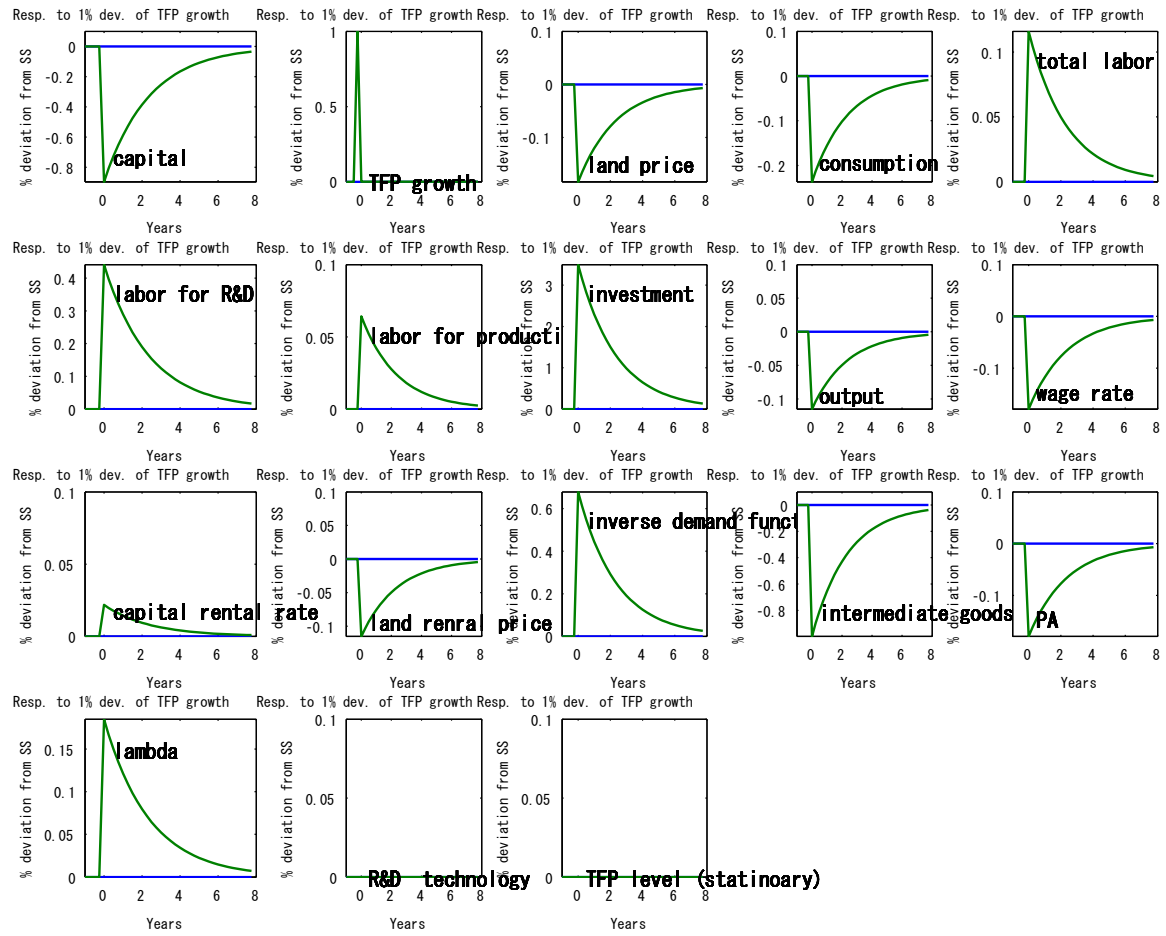


FIGURE 4: IMPULSE RESPONSE TO TFP GROWTH; NO COLLATERAL CONSTRAINT